

New ideas in control software for LR-systems with remote accessible, autonomous process cells

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(in combination with VLBI in cooperation with DLR and MPIfR)

Future requirements

LR

See „The History and Future of Satellite Laser Ranging“⁽²⁾:

- [...] High Level of Automation [...] Fully automated [...] Semi-automated: Single Operator or Remote Operation [...]
- [...] Kilohertz Systems [...]

See „The SLR 2000 Pseudo Operator“⁽³⁾:

- „[...] SLR 2000 Pseudo Operator (POP) controls or directs all aspects of the automated SLR 2000 system. [...] POP will monitor the health and safety of the system foremost and control the acquisition and tracking [...] of the satellites.“

VLBI

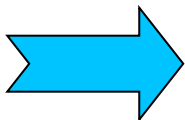
See IVS Memorandum 2006-008v01: VLBI2010⁽¹⁾:

- „[...] Increase observation density [...]“
- „[...] For the highest accuracy the global networks must be tied together. [...]“
- „[...] Automate operations and procedures at all stages [...] Flexibility to add/subtract stations on short notice [...] Automated diagnostic procedures and notification of personel when necessary [...]“
- „[...] Monitoring [...] will make it possible to account for factors [...]“
- „[...] new observing strategies [...]“

GNSS

See NTRIP: „Nutzung der Internet-Radio-Technologie zur Übertragung von GNSS-Daten“⁽⁴⁾:

- „[...] Echtzeitübertragung von GNSS-Daten [...]“
- „[...] Möglichkeit der Fernwartung [...]“



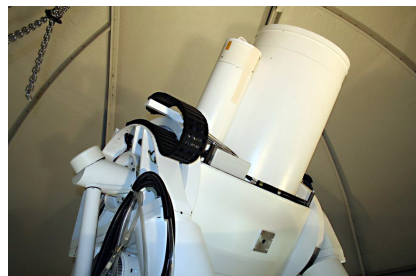
Flexible, remote accessible, reliable, independent, automated and safe systems (throughout all technical levels)

New ideas exemplary at the Satellite Observing System Wetzell



New ideas exemplary at the Satellite Observing System Wetzell

The components



Biaxialtelescope (50cm receive, 16cm send) Carl Zeiss AG Jena

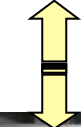


Dome, Baader Planetarium GmbH



1kHz Ti:SAP Laser: 850nm / 425nm (IR / blue), HighQ Laser and Thales

Data-centers



Database (Dell Power Edge)

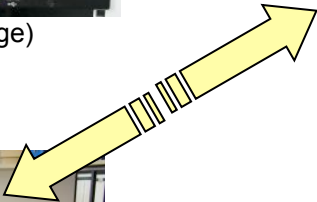


Controlsystem (Industry PC)



Control system (MCU, Sensor)

Director



Sensicam, webcams and video cams



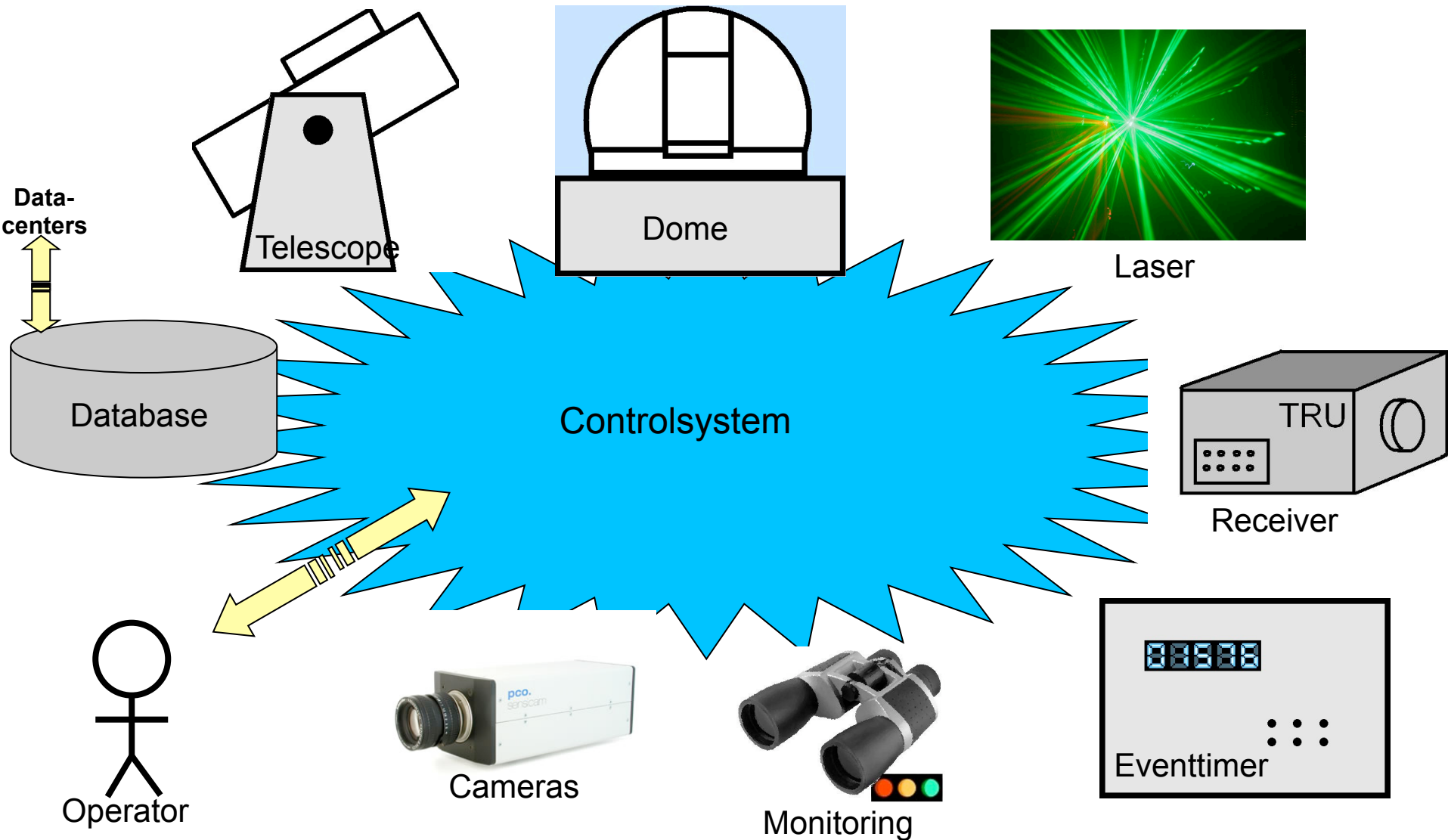
Systemmonitoring (Boxer-PC, serial modules, SPS)



Eventtimer (1.2ps resolution)

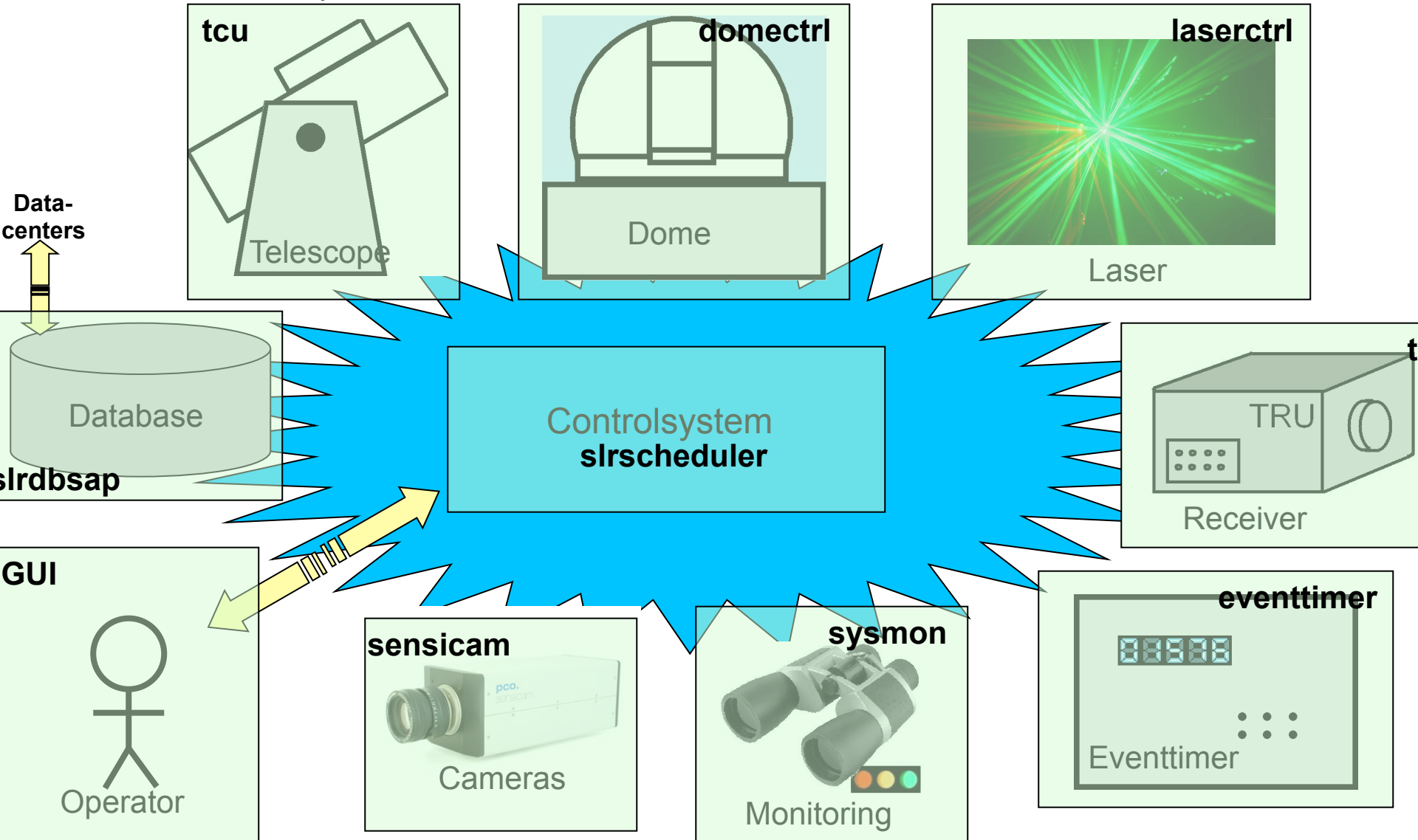
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General view onto the different devices



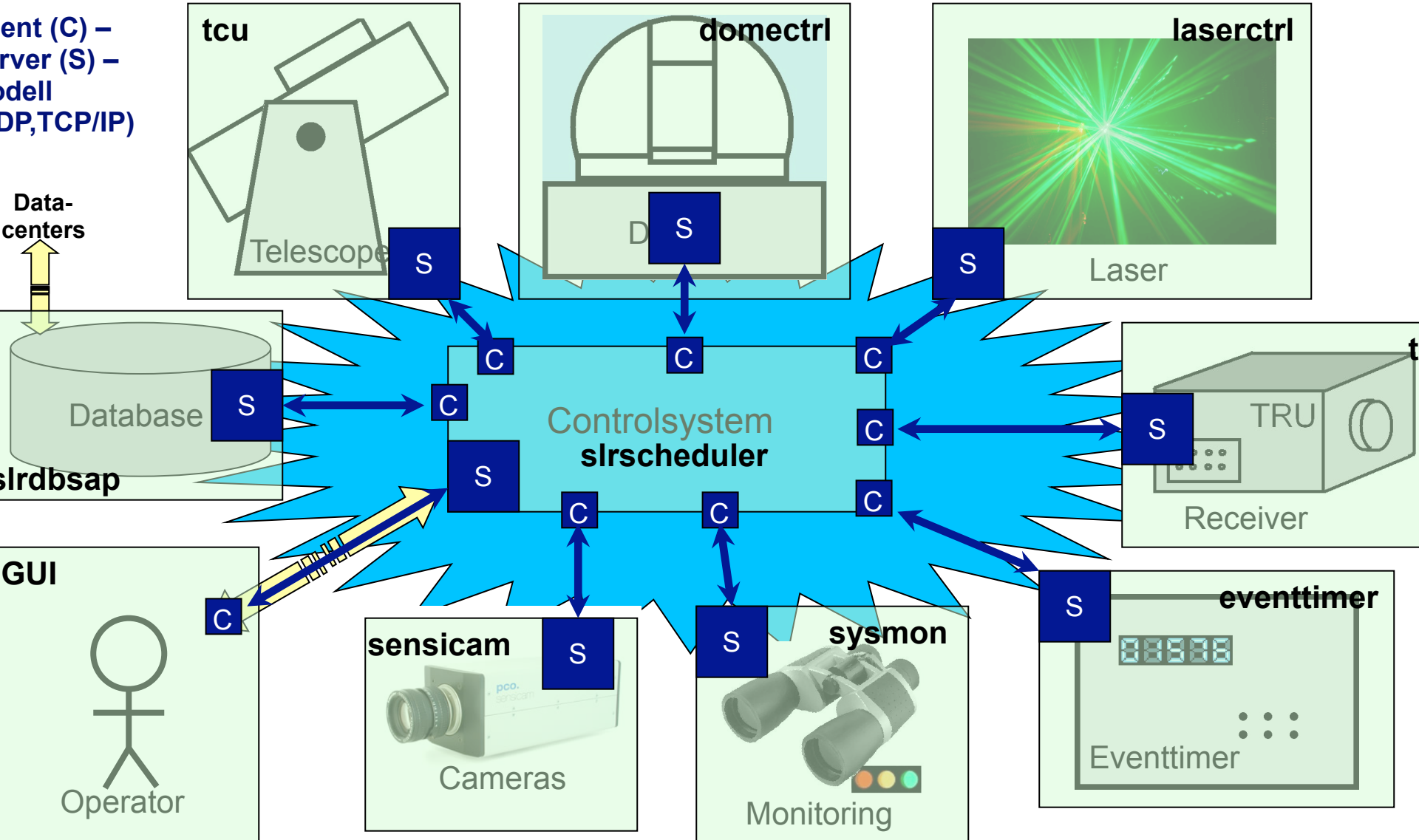
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Representation of the different devices with software modules



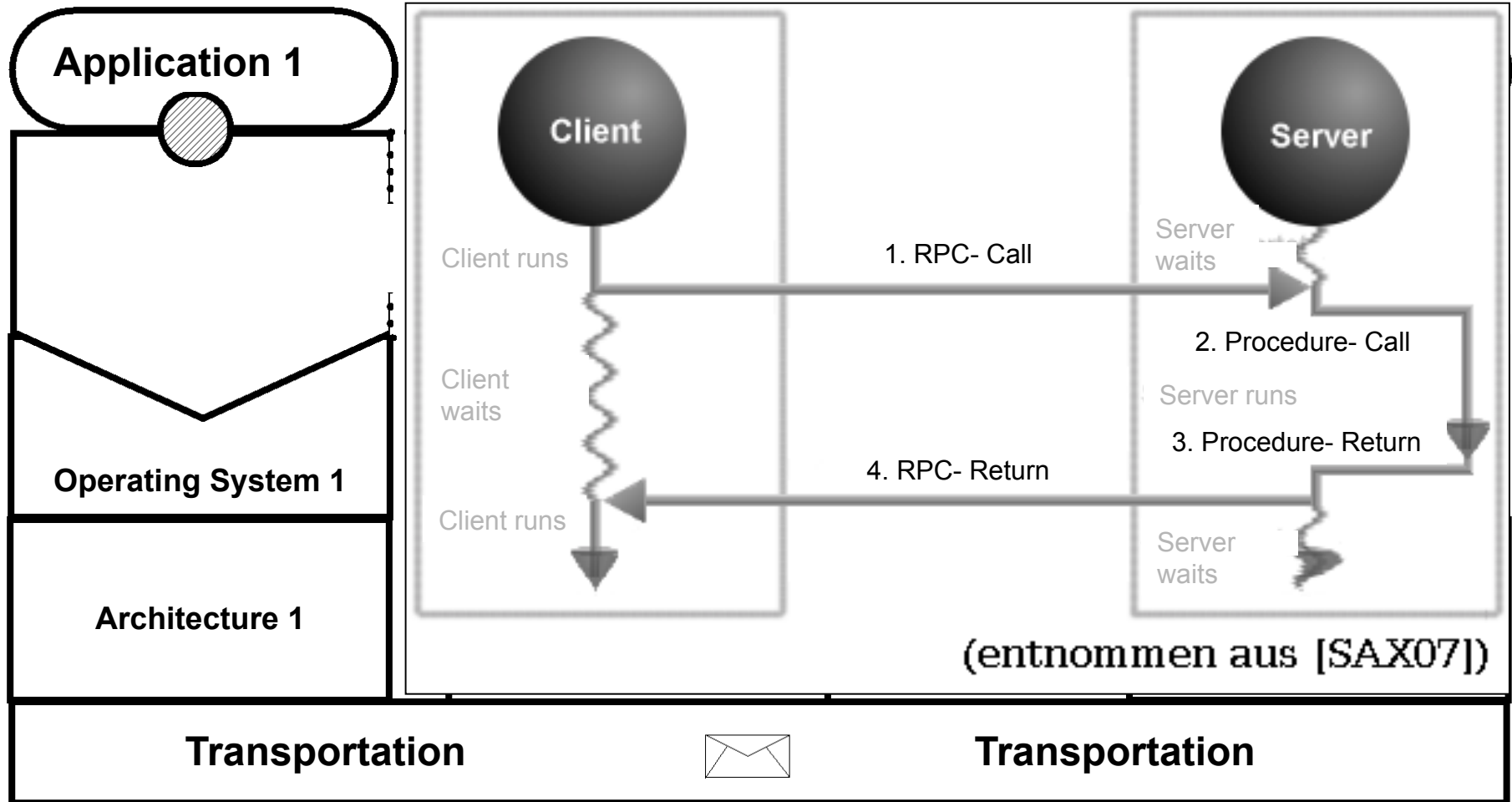
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Communication platform to connect the software modules (spatial separation)



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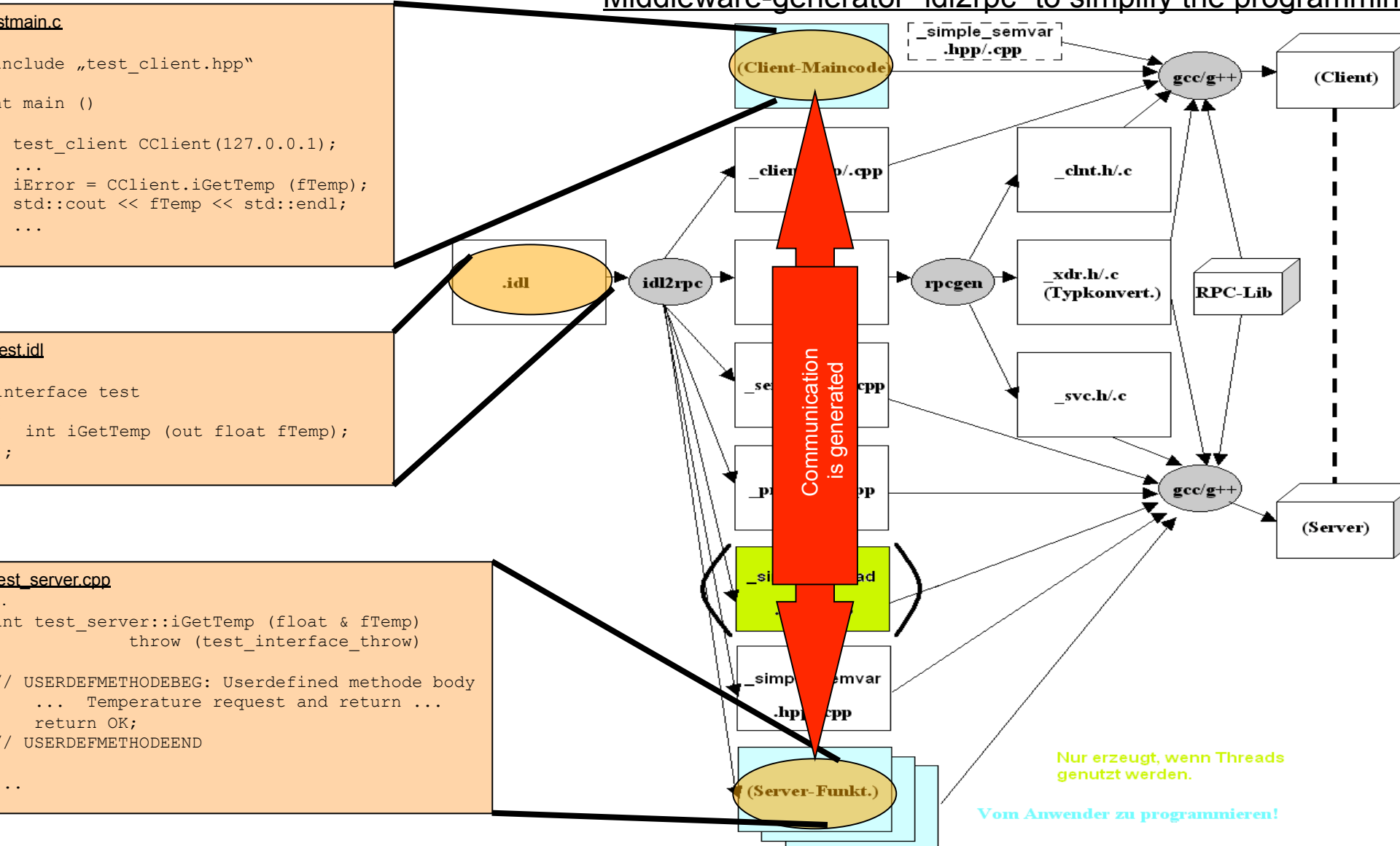
Middleware as communication platform



(nach [PUD01] a.a.O. S. 25)

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Middleware-generator "idl2rpc" to simplify the programming



Interface description – middleware generator

Middleware-generator to simplify the programming: interface definition example

```
const MYCONST1 = 0;
const MYCONST2 = 0x3333;
const MYCONST3 = 12345;
const MYCONST4 = "Hallo";
const MYCONST6 = MYCONST1;
```

```
typedef struct {
char cVar1;
char cVar2;
char cVar3;
char cVar4;
} MYTYPE;
```

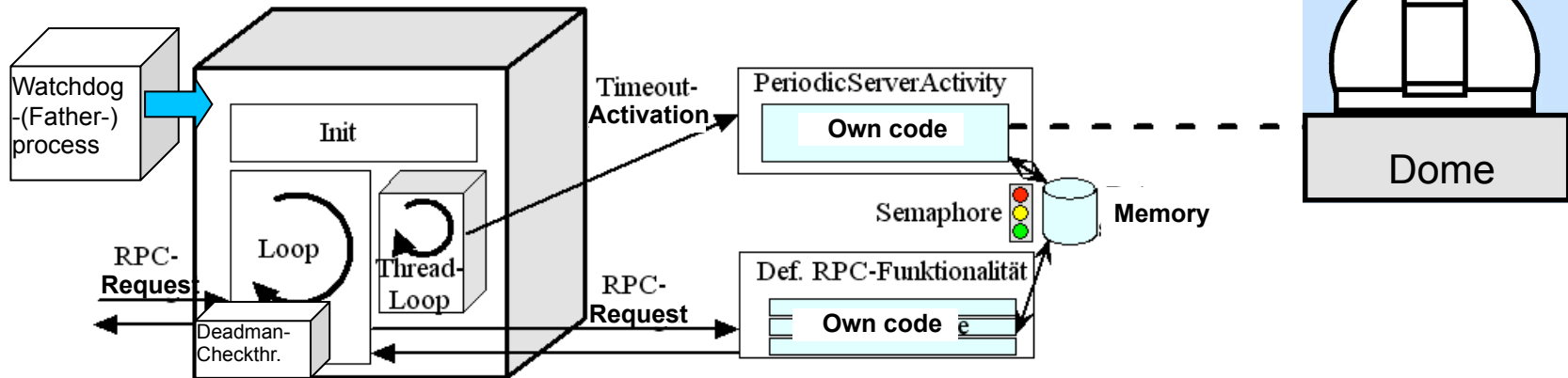
```
typedef struct {
unsigned int iVar1;
int iVar2;
MYTYPE SVar3;
} MYTYPE_COMBINATION;
```

```
interface test
{
// This is a comment
void vFunc ();
int iGet ();
unsigned int uiGet ();
void vSet (in int iVal);
void vSetUnsigned (in unsigned int iVal);
void vGet (out int iVal);
void vSetAndGet (inout int iVal);
void vSetString (in string strText);
void vGetString (out string strText);
void vSetAndGetString (inout string strText);
void vSetMulti (in int iVal, in string strText);
void vGetMulti (out int iVal, out string strText);
void vSetAndGetMulti (inout int iVal, inout string strText);
void vSetArray (in unsigned int Array <>);
void vGetArray (out unsigned int Array <>);
void vSetAndGetArray (inout unsigned int Array <>);
void vSetMultiArray (in unsigned int Array <><><>);
void vGetMultiArray (out unsigned int Array <><><>);
void vSetAndGetMultiArray (inout unsigned int Array <><><>);
};
```

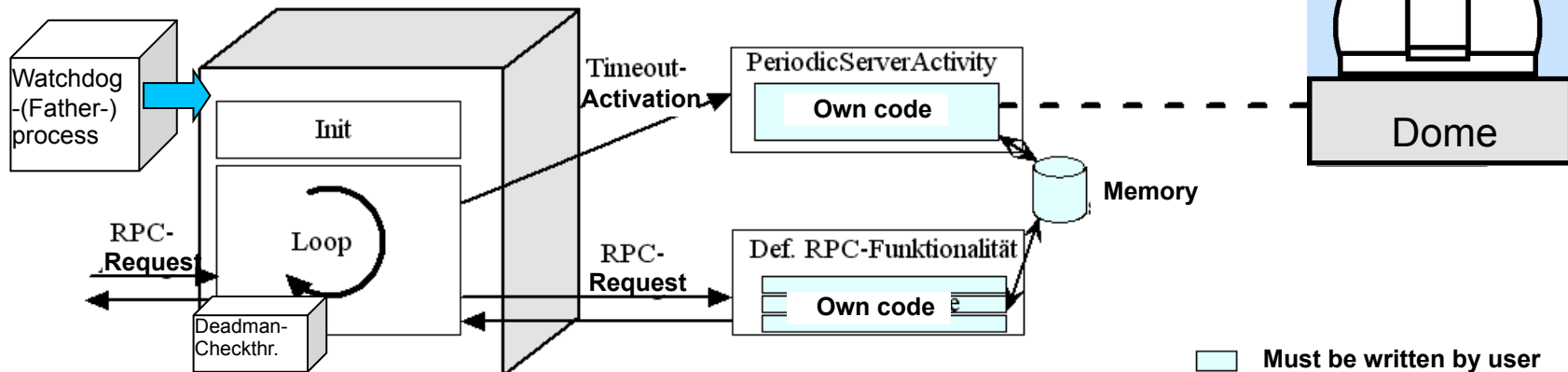
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Autonomous process cells on the basis of the middleware-generator "idl2rpc"

Case 1: Hard timing



Case 2: Weak timing



Must be written by user

New ideas exemplary at the Satellite Observing System Wetzell

User interaction with graphical user interface

- Separation of control and presentation logic
- Interchangeability of presentation layer (console shell (ncurses), graphical user interface (wxWidgets), web access via Browser, web service, ...)
- Remote controllable via client-server-architecture on idl2rpc-middle-ware
- Modularity in window units and additionally possible, separately created administration user interfaces for each device
- Basis for graphical user interface: wxWidgets (C++ based Open-Source-Framework for platform independent development of graphical user interfaces)

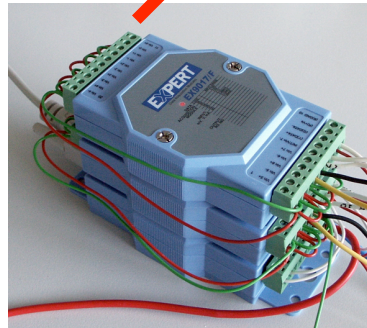
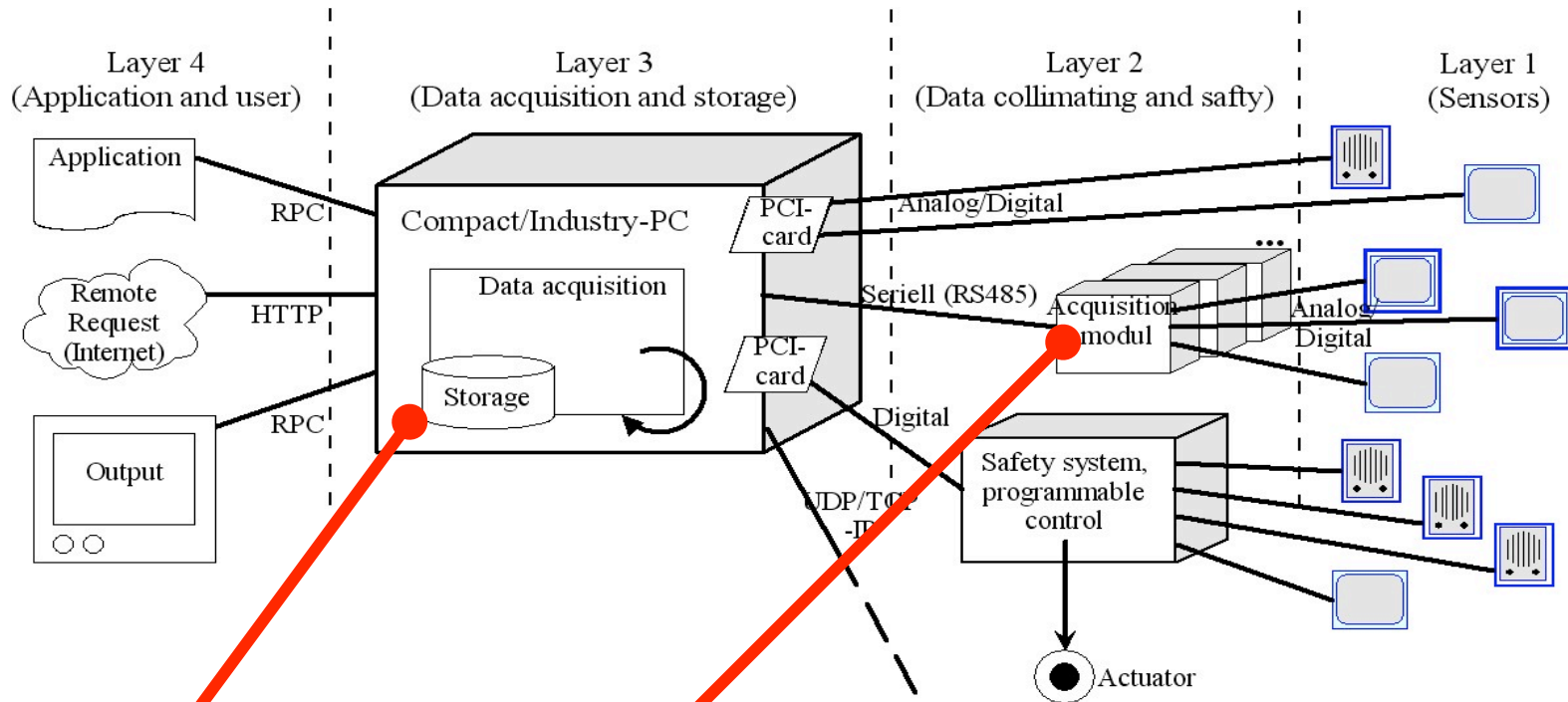
The screenshot displays the SOS-W graphical user interface, which is a complex dashboard for satellite observation. It features several key components:

- Satellite List:** A table showing satellite data with columns for priority, target_name, rise_time, transit_elevation, set_time, and ephemeris_source_id.

priority	target_name	rise_time	transit_elevation	set_time	ephemeris_source_id
3.19	etalon2	2008-07-09 12:47:48	53.16584	2008-07-09 16:42:53	HTS6901
3.02	giovea	2008-07-09 13:05:01	67.852233	2008-07-09 19:28:08	ESA6911
- Telescope Control:** A window for controlling the telescope, showing Azimuth (49989) and Elevation (59986) with numerical input fields and buttons for adjustment. It also displays the Telescope epoch (09:07:08 15:09:30) and various status indicators like On Target, Error, Tracking, and Sun.
- Environmental Sensors:** A section displaying real-time data for Temperature (16.7°C), Humidity (70%), and Atm. Pressure (945.6 hPa).
- pET Control:** A window for controlling the pET system, including State (Error, Calib), Mode (Range, Calib), and Time (00:00:00) settings.
- Target Information:** A table on the right providing details for the selected target 'etalon2', including RiseTime, Trans.Time, Max.Elevat., SetTime, Obs. File, Ephem. Source, SunAvoid.Entry, and SunAvoid.Exit.
- Navigation and Settings:** A sidebar on the left contains icons for Observer, SLR Devices, Dome Control, Telescope Control, Camera Control, pET Control, Meteo Ctrl, Clock Ctrl, SLR-DB, and Mount Model.

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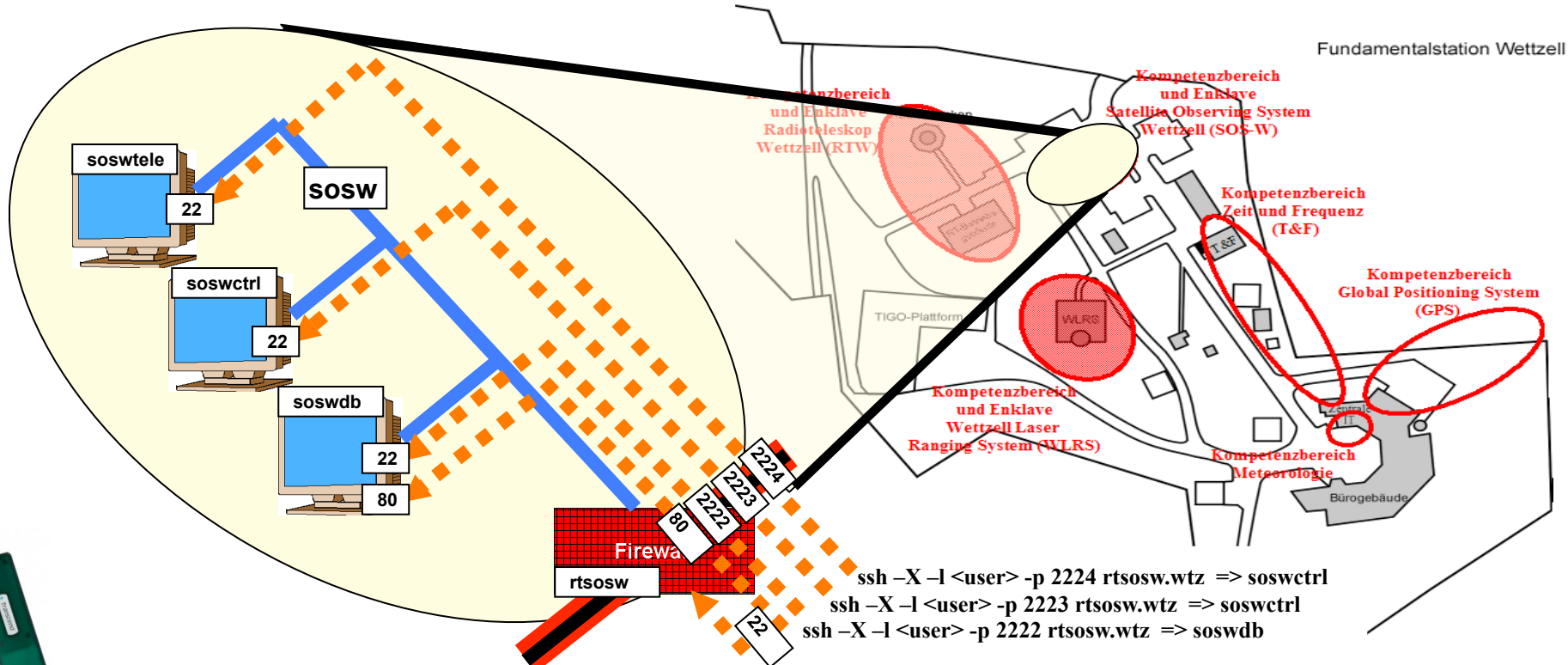
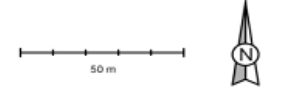
Additional control of the system by system monitoring



- Standard equipment on standard, robust architectures
- Modular, multi-layer system
- Open for several devices and sensors
- Passive system for monitoring without actuators
- Linux-operating system (maybe minimal installation)
- Open Source
- C/C++
- Communication internal with idl2rpc-generator
- Vendor independence

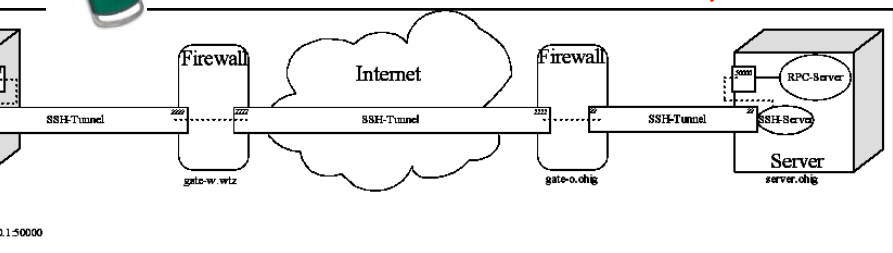
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Security by usage of security enclaves



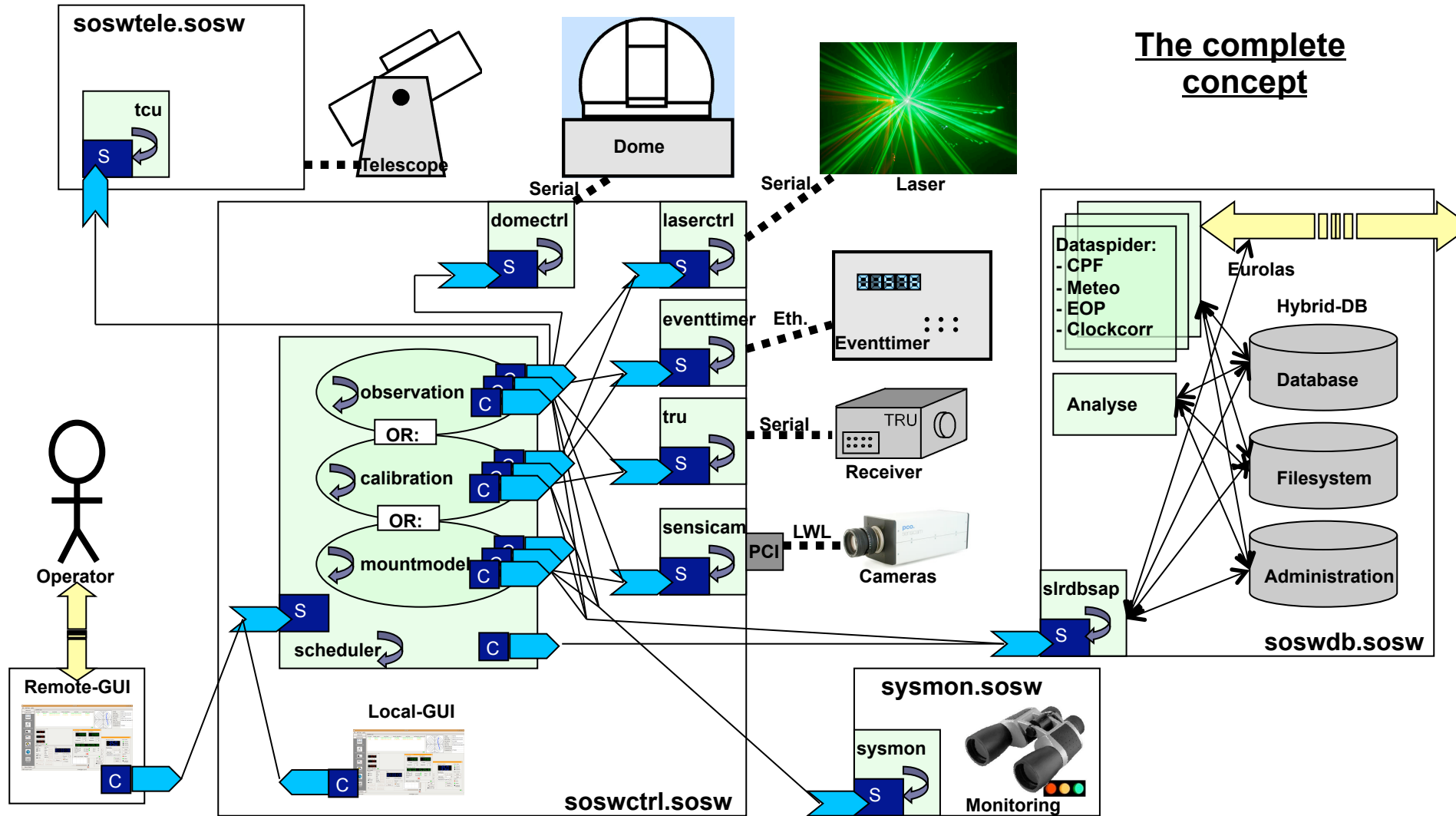
```
ssh -X -l <user> -p 2224 rtsosw.wtz => soswctrl
ssh -X -l <user> -p 2223 rtsosw.wtz => soswctrl
ssh -X -l <user> -p 2222 rtsosw.wtz => soswdb
```

```
ssh -X -l <user> rtsosw.wtz => rtsosw
```



Ursprünglicher Stationsplan von Dr. Klügel, FS Wetzell

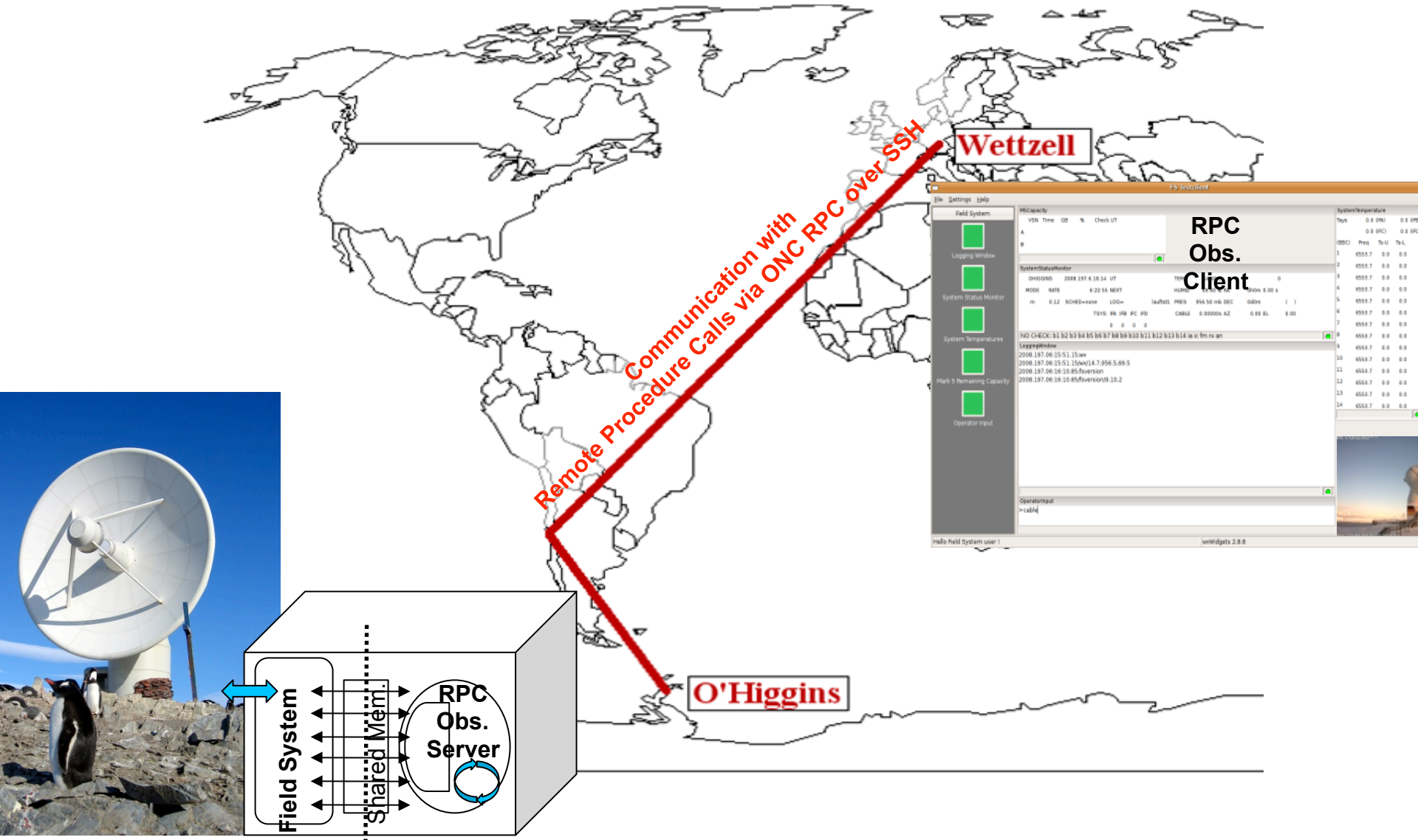
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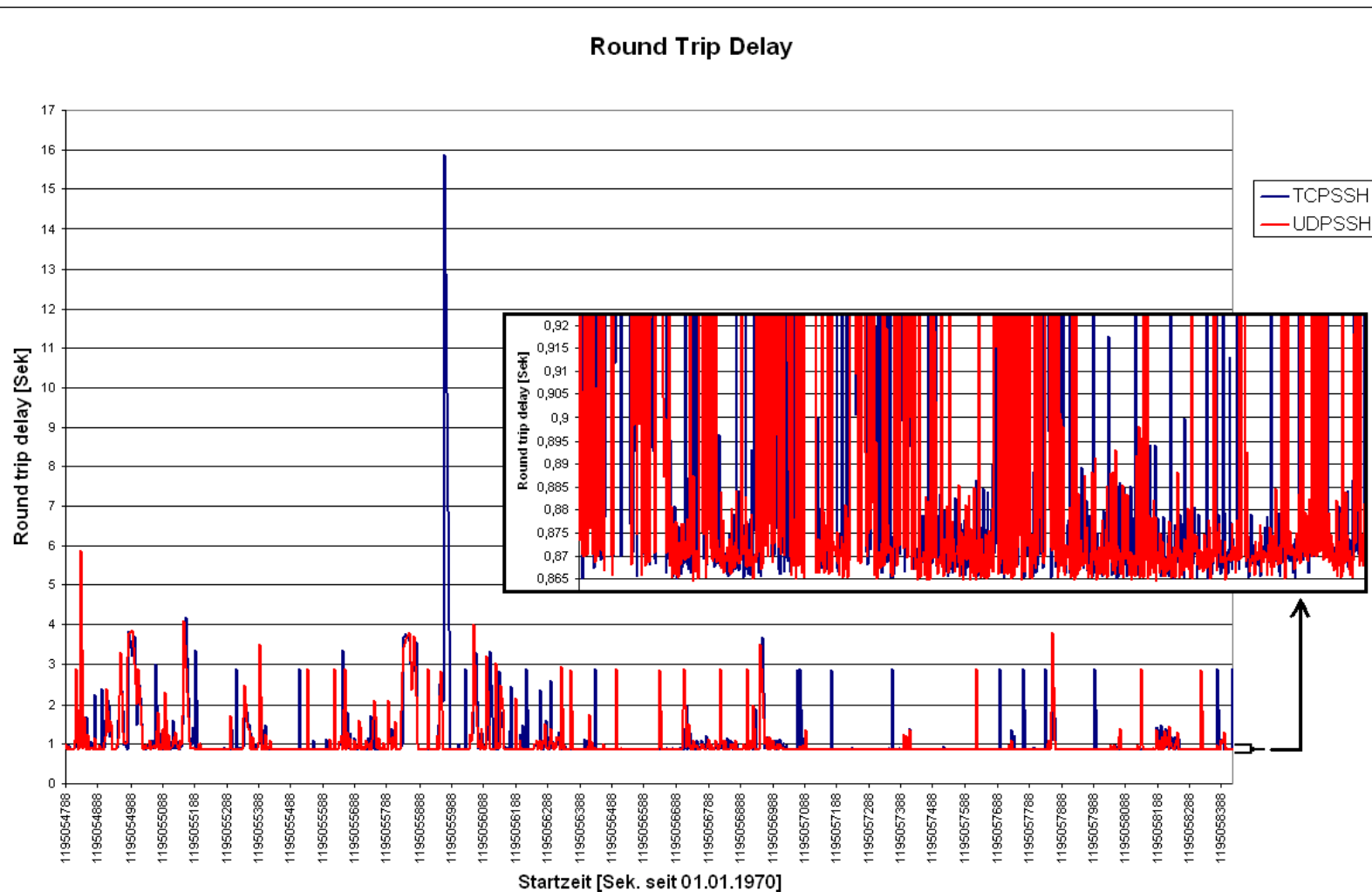
Remote control example with VLBI station GARS O'Higgins



The idea – remote control of VLBI at O’Higgins/Antarctica



The idea – remote control of VLBI at O’Higgins/Antarctica



First test during
VLBI-campaign
02/2007
(first remote con-
trolled experimen-
t is planned for cam-
paigne 02/2008)

Thank you!